MITSUBISHI

MELSEC-I/O Link Remote I/O System Master Module Type AJ51T64/A1SJ51T64

User's Manual



SAFETY PRECAUTIONS

(Read these precautions before using.)

When using Mitsubishi equipment, thoroughly read this manual and the associated manuals introduced in this manual.

Also pay careful attention to safety and handle the module properly. These precautions apply only to Mitsubishi equipment. Refer to the CPU module user's manual for a description of the PLC system safety precautions.

These ● SAFETY PRECAUTIONS ● classify the safety precautions into two categories: "DANGER" and "CAUTION".



Depending on circumstances, procedures indicated by <u>A</u> CAUTION may also be linked to serious results.

In any case, it is important to follow the directions for usage.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

to opera	safety circuits external to the PLC that ensure that the system as a whole will continue ate safely even in the event of an external power supply fault or PLC failure. to provide such circuits may lead to accidents caused by erroneous outputs or tion.
opera - suc (2) If the	igure emergency stop circuits, protective circuits, interlock circuits for opposing ations such as forward/reverse, and interlock circuits to prevent damage to the machine ch as those for upper and lower positioning limits - external to the PLC. PLC detects either of the following error statuses it stops operation and turns all buts OFF:
pr • El	ctuation of the power supply module's overcurrent protection device or overvoltage rotection device rror detected by the self-diagnosis function at the PLC CPU, such as a watchdog mer error.

Local Control section of output modules, which cannot be detected by the PLC CPU, may cause all outputs to go ON. A failsafe circuit must therefore be configured external to the PLC to ensure that the machinery will operate safely. For examples of failsafe circuits, refer to the User's Manual for the CPU module. (3) Failures of output module relays and transistors may lead to outputs going ON or OFF. Provide external circuits to monitor output signals whose failure could result in serious accidents. When a data link communication error occurs, the status shown below will be established at the faulty station. In order to ensure that the system operates safely at such times, configure an interlock circuit in the sequence program. Failure to provide such a circuit may lead to accidents caused by erroneous outputs or malfunction.

(1)All inputs from remote I/O stations go OFF

(2)All outputs from remote I/O stations go OFF

• Do not bundle control lines or communication wires together with main circuit or power lines, or lay them close to these lines.

As a guide, separate the lines by a distance of at least 100 mm, otherwise malfunctions may occur due to noise.

[INSTALLATION PRECAUTIONS]

- Use the PLC in an environment that conforms to the general specifications in the manual. Using the PLC in environments outside the ranges stated in the general specifications will cause electric shock, fire, malfunction, or damage to/deterioration of the product.
- When using an A1SJ51T64 master module, make sure that the module fixing projection on the base of the module is properly engaged in the fixing hole in the base unit before mounting the module, and then tighten the module mounting screws to the stipulated torque. Failure to mount or secure the module properly could result in malfunction, failure, or in the module falling. When using an AJ51T64 master module, make sure that the module fixing projection on the base of the module is properly engaged in the fixing hole in the base unit before mounting the module. Failure to mount the module properly could result in malfunction, failure, or in the module falling.
- Secure remote I/O modules properly on a DIN rail or with mounting screws. If a module is not secured properly, it could fall.
- Tighten screws to within the stipulated torque range. Loose screws could cause falling of the module, short circuits, and malfunction. Overtightening could damage the screws or module, and cause falling of the module, short circuits, and malfunction.

[WIRING PRECAUTIONS]

DANGER

- Switch off all phases of the power supply externally before starting installation or wiring work. Failure to do so could result in electrical shocks and equipment damage.
- After installation and wiring is completed, be sure to attach the terminal cover provided before switching the power ON and starting operation. Failure to do so could result in electrical shock.

 Be sure that the communication cable connected to the module is kept in ta duct or fixed with cramps. Failure to do so may cause a damage to the module or cables due to dangling, shifting or inadevertent handing of cables, or misoperation because of bad cable contacts. 					
• You must ground the FG terminal to a ground exclusive to the PLC.					
 Carry out wiring to the PLC correctly, checking the rated voltage and terminal arrangement of the product. Using a power supply that does not conform to the rated voltage, or carrying out wiring 					
incorrectly, will cause fire or failure.					
 Tighten the terminal screws to the stipulated torque. Loose screws will cause short circuits, fire, or malfunctions. Overtightening could damage the screws or module, and cause falling of the module, short circuits, and malfunction. 					
 Do not grab on the cable when removing the communication cable connected to the module. When removing the cable with a connector, hold the connector on the side that is connected to the module. Pulling the cable that is still connected to the module may cause a damage to the module or cable, or misoperation due to bad cable contacts. 					
 Tighten screws to within the stipulated torque range. Loose screws could cause falling of the module, short circuits, and malfunction. Overtightening could damage the screws or module, and cause falling of the module, short circuits, and malfunction. 					
[STARTING AND MAINTENANCE PRECAUTIONS]					

- Do not touch terminals while the power is ON. This will cause malfunctions.
- Switch off all phases of the power supply externally before starting cleaning or re-tightening the terminal screws. Carrying out this work while the power is ON will cause failure or malfunction of the module. Loose screws could cause short circuits, fire, and malfunction. Overtightening could damage the screws or module, and cause falling of the module, short circuits, and malfunction.

- Read the manual thoroughly and confirm safety before connecting a peripheral device to the CPU during operation and performing an online operation (particularly program change, forced output, or operation status change). Misoperation could damage the machine and cause accidents.
- Do not disassemble or modify any module. This will cause failure, malfunction, injuries, or fire.
- Switch the power OFF before mounting or removing the module. Mounting or removing it with the power ON can cause failure or malfunction of the module.
- Before touching the module, be sure to touch ground metal or similar material to discharge static electricity from human body, etc. Failure to do so can cause the module to fail or malfunction.

[DISPOSAL PRECAUTIONS]

• When disposing of this product, handle it as industrial waste.

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INTRODUCTION

Thank you for choosing the Mitsubishi MELSEC-A Series of General Purpose Programmable Controllers. Please read this manual carefully so that the equipment is used to its optimum. A copy of this manual should be forwarded to the end User.

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1. GENERAL DESCRIPTION

This user's manual describes the specifications, connection, and programming of the AJ51T64/A1SJ51T64 MELSEC-I/O LINK Remote I/O System Master Module (hereafter called the "master module").

1.1 Features

MELSEC-I/O LINK is an easily programmable remote I/O system which has simple wiring and does not require troublesome parameter settings.

- (1) Up to 128 I/O points can be controlled When used with an 8-point/16-point I/O unit (AJ55TB32-8[][], AJ55TB32-16[][]), a single master module can control a maximum of 128 points (input: 64 points, output: 64 points).
- (2) Flexible connection Bus connection allows T-junctions and makes terminal resistors unnecessary, so connection is flexible.
- (3) Prevention of communication system malfunctions Bus connection prevents the entire system from going down simply because one station is down.
- (4) Programming is simple.Programming is possible using X/Y devices only.

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2. SYSTEM CONFIGURATION

2.1 System Configuration



- Applicable CPUs The master modules can be used with the following PLC CPUs (including PLC CPUs with link functions).
 - (a) When using AJ51T64:

(4)	Minori using Aug 110-	τ,	
	 A0J2CPU^{*1} 	 A0J2HCPU^{*1} 	• A1CPU
	 A2CPU(S1) 	 A3CPU 	A1NCPU
	 A2NCPU(S1) 	A3NCPU	A3MCPU
	A3HCPU	 A2ACPU(S1) 	• A3ACPU
	 A2UCPU(S1) 	A3UCPU	A4UCPU
	 A73CPU(S3) 	 A81CPU 	
	 Q2ACPU(S1) 	 Q3ACPU 	Q4ACPU
		1T64 in combination v to a type A6⊟B exten	with one of the PLC CPUs sion base unit.
(b)	When using A1SJ517	Г64:	
• • •	 A1SCPU(S1) 	A1SCPUC24-R2	 A1SJCPU(S3)
	A2SCPU(S1)	 A1SHCPU 	• A1SJHCPU
	A2SHCPU(S1)	 A2ASCPU(S1) 	
	• A52GCPU(T21B)*2	Q2ASCPU(S1)	 Q2ASHCPU(S1)
			· · /

*When using the A1SJ51T64 in combination with one of the PLC CPUs marked *2, mount it to a type A1S6 B extension base unit.

- (2) Number of modules that can be loaded Any number of modules that does not exceed the number of I/O points of the applicable CPU can be used.
- (3) Loading slot

The master module can be loaded into any slot of the base unit except in the following cases.

Note that the power capacity may become insufficient if the module is loaded onto an extension base unit without a power supply module (A1S52B(S1), A1S55B(S1), or A1S58B(S1)).

If loading the master module on an extension base unit that does not have a power supply module, select a power supply module, a main base unit, an extension base unit, and extension cable, by considering the following points.

- 1) Current capacity of the main base unit
- 2) Voltage drop in the main base unit
- 3) Voltage drop in the extension base unit
- 4) Voltage drop in the extension cable

(4) Data link system

The master module can be loaded at any master, local, or remote I/O stations in data link system.

(5) Network system

The master module can be mounted at any control, normal, master, or remote I/O station in the network system.

REMARK

For details on calculating the number of I/O units that can be loaded and the voltage drop, refer to the user's manual for the PLC CPU to be used.

2.2 Notes on Configuring a System

With an I/O link, consider the following points when designing the system to prevent erroneous inputs/outputs to/from the remote I/O units.

- (1) Measures against erroneous input and output when the power is turned ON or OFF
 - (a) When turning on the power

Recommendation 1: Switch ON both the power supply to the remote I/O unit and the external power supply to the master module before switching ON the power supply to the PLC CPU.

Recommendation 2: Simultaneously switch on the power supplies of the remote I/O unit and the master module and the power supply to the PLC CPU.

(b) When turning off the power supply

Recommendation 1: Switch off the power supply to the PLC CPU before switching off both the power supply to the remote I/O unit and the external power supply to the master module.

Recommendation 2: Simultaneously switch off the power supply to the remote I/O unit, the power supply to the PLC CPU, and the external power supply to the master module.

(2) Measures against erroneous input due to momentary power interruption

Erroneous input may occur if the power to a remote I/O unit is momentarily interrupted.

(a) Cause

The hardware of the remote I/O units internally converts the 24 VDC power supply for the I/O unit into 5 V DC before use. If a momentary power interruption occurs at a remote I/O unit, the following condition applies:

(Time lapse until the internal 5 VDC of the remote I/O unit is turned OFF) < $(ON \rightarrow OFF \text{ response time of the } 1/O \text{ unit}).$

This will cause erroneous input if an I/O refresh occurs during period (1) as shown in the chart below.

Externally supplied 24 VDC (for power supply to the I/O unit and as the input external power supply)	
Internal 5 VDC	
Input (Xn)	
When the input ex (Xn) is turned OFF	ernal power supply is turned OFF, the input after the ON \rightarrow OFF response time.

(b) Measures against erroneous input Connect the power supply module and the stabilized power supply to the same power supply.



3. SPECIFICATIONS

This section gives the general specifications and performance specifications.

3.1 General Specifications

Table 3.1 gives the general specifications of A-series programmable controllers.

ltem	Specifications									
Operating ambi- ent temperature	0 to 55°C	0 to 55°C								
Storage ambient temperature	-20 to 75°C									
Operating ambi- ent humidity	10 to 90 %RH, no	dewing								
Storage ambient humidity	10 to 90 %RH, no	dewing								
		Frequency	Acceleration	Amplitude	Sweep Count					
Vibration resis- tance	Conforms to *2 JIS C 0911	10 to 57 Hz		0.075 mm (0.003 in.)	10 times					
		57 to 150 Hz	9.8 m/s ² (1 g)		*1(1 octave/minute)					
Shock resistance	Conforms to JIS C	0912 (15 g x 3 time	es in 3 directions) *2		• • • • • • • • •					
Noise durability	By noise simulator	at 1500 Vpp noise	voltage, 1 µs noise v	vidth and 25 to 60 H	Hz noise frequency					
Withstanding voltage	1500 VAC for 1 mi 500 VAC for 1 min	nute across AC exte ute across DC exte	ernal terminals and g rnal terminals and gr	round ound						
Insulation resis- tance		5 M Ω or greater measured with 500 VDC insulation resistance tester across AC external terminals and ground								
Grounding	Class 3 grounding	. If proper groundin	g impossible, connec	ct the grounding wir	re to the panel.					
Operating at- mosphere	Free of corrosive g	gases. Dust should	be minimal.							
Cooling method	Self-cooling									

Table 3.1 General Specifications

REMARKS

- *1 One octave means a change from the initial frequency to double or half frequency. For example, all of the following are changes of one octave: 10 Hz to 20 Hz, 20 Hz to 40 Hz, 40 Hz to 20 Hz, and 20 Hz to 10 Hz.
- *2 JIS stands for Japan Industrial Standards.

3.2 Performance Specifications

The Performance specifications of the MELSEC-I/O LINK (Master Module) are listed below.

	Items	Specifications						
		AJ51T64	A1SJ51T64					
	x. number of trol I/O points	128 points (if the same numbers a	are used for X and Y.)					
1/0	refresh time	Approx. 5.4 ms (regardless of the	e number of points)					
Cor cab	nmunication le	0.75 mm ² or larger twisted pair ca 0.75 mm ² or larger cabtyre cable	able					
	Communication speed	38400 bps						
	Communication method	Register insertion method						
cations	Synchronizatio n method	Combination of frame synchroniza methods	ation and bit synchronization					
specifi	Error control system	Parity check						
cation	Transmission channel	Bus (T-junctions possible, terminal resistors unnecessary)						
Communication specifications	Transmission distance	Overall distance: 200 m (656 ft.)						
Cor	Max. number of remote I/O units connectable as stations	16 stations per master module						
Error (RUN) indication/output		Indication by LEDs The PC CPU detects errors as "blown fuse". External output with RUN A/RUN B						
Number of occupied I/O points		64 points (I/O allocation: 64 output points)*						
External power supply voltage		21.6 to 27.6 VDC (for the transmission channel)						
External power supply current consumption		90 mA (TYP 24 VDC)						
con	rnal current sumption /DC)	115 mA	115 mA					
Wei	ght (kg)[lb]	0.35 [0.77]	0.3 [0.66]					

	Table 3.	2 Performance	Specifications
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* If only a few remote I/O units are used, perform I/O allocation with a peripheral device to decrease the number of occupied I/O points to 16, 32, or 48.

For details on the noise durability, dielectric withstand voltage, insulation resistance, etc., of a PLC system that uses the AJ51T64/A1SJ51T64, refer to the power supply module specifications in the CPU module User's Manual.

REMARK

The following is a schematic illustration explaining the system of communication. The illustration shows that the PLC CPU and master module always communicate to each other the I/O data received from and to be sent to the 16 stations.



3.3 Handling of I/O Data of Faulty Stations

All I/O data of a remote I/O unit that has become a faulty station due to a disconnection or other problem is "OFF".



3.4 Cable Specifications

This section gives the specifications of the twisted pair cables and the cabtyre cables.

(1) Cable specifications

Table 3.3 shows the specifications of the twisted pair cables and cabtyre cables.

Item	Specifications						
Cable type	Shielded twisted pair cable	Cabtyre cable					
Logarithm	0.75 mm ² x 1P	0.75 mm ² x 2C					
Conductor resistance (20 °C)	29 Ω /km or less						
Electrostatic capacity (1 kHz)	75 nF/km or less						
Characteristic impedance (100 kHz)	100 Ω on the average						
Insulation resistance	n resistance 500 MΩ/km or greater						
Withstanding voltage	500 VDC/minute or greater						
Outside dimensions	φ8.5 mm or smaller	φ9 mm or smaller					

(2) Recommended cables

This section gives the model names, specifications, and manufacturers of the recommended cables.

Item	Specifications					
Model	KNPEV-SB 0.75SQ x 1P	KNEV-SB 0.75SQ x 2C				
Cable type	Shielded twisted pair cable	Unshielded cabtyre cable				
Logarithm	0.75 mm ² x 1P	0.75 mm ² x 2C				
Conductor resistance (20 °C)	26.3 Ω/km or less					
Electrostatic capacity (1 kHz)	60 nF/km or less					
Characteristic impedance (100 kHz)	90 Ω on average					
Insulation resistance	10,000 MΩ/km or greater					
Withstanding voltage	1000 VAC					
Cross-section	Braided shield Vinyl sheath	Vinyl sheath Yellow White Two cores: 0.75 mm ² PE insu- lated conductors				
External dimensions	φ7.5 mm or less	φ7 mm or less				

Table 3.4	4	Recommended	Cables
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The following are the other recommended cables and their manufacturers.

Model	Туре
SPEV(SB)-0.75-1P	Shielded twisted pair (1P)
KMPEV-SB CWS-178 0.75SQ x 1P	Shielded twisted pair (1P)
2PNCT 0.75SQ x 2C	Two-core cabtyre
DPEV SB 0.75 x 1P	Shielded twisted pair (1P)
VCT 0.75 x 2C	Two-core cabtyre
D-KPEV-SB 0.75 x 1P	Shielded twisted pair (1P)
IPEV-SB 1P x 0.75	Shielded twisted pair (1P)

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4. PRE-OPERATION SETTINGS AND PROCEDURES

4.1 **Pre-Operation Procedures**

The following flowchart shows the pre-operation settings and procedures.



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4.2 Nomenclature and Settings

4.2.1 Master module

(1) AJ51T64



(2) A1SJ51T64



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No.	Name and Appearance	Description					
(1)	ON LINE STATION	"0" to "F" in ON : Comm OFF: Comm * To preven	the drawin nunication p nunication r	g to the performe not perfor cation err	he connected remote I/O units. (Factory setting: all ON) he left represent the 16 station numbers. med (with error check) erformed (no error check)		
	LED	Nan	ne	LED status	Description		
	AJ51T64	24 V		ON	External power supply voltage (24 VDC) is normal.		
	50 0 02 1 10 0 3 4 0 04 1 0 05 5 0 06 5 0 07 1			OFF	External power supply voltage (24 VDC) is insufficient.		
	0 0 8 1 0 0 9 1 0 0 8 1 0 0 9 1 0 0 8 1 0 0 0 9 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RUN *1		ON	All data received from the remote I/O units activated with the ONLINE STATION switches is normal.		
(2)				OFF	Abnormal data has been received from a remote I/O station ("SHORT", "OPEN", or "PARITY" error has occurred). Meanwhile, communication is continued with normal stations.		
τ.		SD		ON	Data is being transferred		
		RD *2		ON	Data is being received.		
	A1SJ51T64 Rát ? 5		SHORT	ON	Short between DATA and DG.		
			OPEN	ON	Disconnection in transmission line, faulty remote I/O station, or power (24 VDC) OFF.		
			PARITY	ON	Abnormal data has been received from a remote I/O station.		
	ERROR STATION 0 to F		ON	Indicates the station number of the remote I/O unit with which communication is not possible			

1: The RUN "OFF" status can also be confirmed with "Blown Fuse (M9000, D9000, and D9100 to 9107)" at the PLC CPU. M9000..... RUN status (blown fuse detected) (SM60)

D9000..... First I/O No. of master module (module No. with blown fuse) (SD60)*

D9100 to 9107 Module No. with blown fuse (details) (SD1300 to SD1307)*

* : Special relays/special registers when using QnACPU

Note: This does not enable identification of remote I/O modules that are down.

*2: The brightness of RD differs according to the number of connected stations. (The fewer the stations, the dimmer it is.)

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No.	Name and Appearance	Description						
	Terminal block	For connecting signals, a power supply, and RUN output to the module. (Size: M4, clamp torque: 100 to 137 N cm (10 to 14 kg cm) [8.8 to 12.32 lb inches]						
		Name						
		DATA	Data	Data				
		DG	Data	Data ground			See Section 5	
	FG (X)	FG	Frar	"CONNECTION OF THE MASTER				
	+24V (X) 24G (X)	+24 V		er supply for sitive)	24 VDC transm	nission	MODULE TO REMOTE I/O UNITS" for details of connection.	
		24 G		er supply for jative)	24 VDC transm	nission	or connection.	
	RUN B	RUN A RUN B	ON	ernal output de RUN LED RUN LED		ON/OFF statu	s of RUN LED	
				Output type		Contact out	out	
				Insulation m	ethod	Relay insula	tion	
				Rated load current	voltage and	24 VDC (res (COSφ=1), 2	sistance load), 240 VAC 2 A/point	
				Min. switchi	ng load	5 VDC 1mA		
				Max. switch	ing voltage	250 VAC 11	0 VDC	
			suo	Response time	OFF→ON	10 ms or les	S	
			Specifications		ON→OFF	12 ms or les	S	
			pecit		Mechanical	20 million or	perations or more	
(3)	(3)		S	Life	Electrical		d operations or more at ritching load and Itage	
						100 thousan 200 VAC an A (COS¢=0	d operations or more at d 1.5 A, or 240 VAC or 1).7)	
							d operations or more at d 1 A, or 240 VAC and)=0.35)	
							d operations or more at 1A, or 100 VDC and 0.1 A)	
1				Max. switch	ing frequency	3600 times/	hour	
				Surge suppr	essor	Varistor		
		External connection	External connection		RUN A RUN B C	511764	RA 7777	

4.2.2 Remote I/O Unit (AJ55TB[][]-[][])





No.	Name and Appearance	Description					
	STATION No.						
(1)	$ \begin{array}{c} $	For selecting a station number between 0 and F. (Factory setting: 0) Also, set the ONLINE STATION setting switches on the master module to prevent errors at the unconnected station numbers. (See Section 4.2.1 for details.)					
	LED	Name	LED status		Description		
	PW RUN SD RD ERR.	PW	ON	Internal 5 V source from	the external power supply is normal.		
	AAAAA	PVV	OFF	Internal 5 V source from	the external power supply is abnormal.		
(2)		RUN	ON	Data reception from the	master module is normal.		
		RUN	OFF	Data reception from the	master module is abnormal.		
		SD	ON	Data is being transferred	to the master module.		
		RD	ON	Data is being received from the master module.			
		ERR.	ON	Data received from the m	naster module is abnormal.		
(3)	$\begin{array}{c} LED \\ 0 & 1 & 2 & 3 \\ \hline \end{array} \begin{array}{c} & & & \\ \end{array} \end{array} \begin{array}{c} & & \\ & & \\ \end{array} \begin{array}{c} & & \\ & \\ \end{array} \end{array}$	Indicate the input/output status.					
		For connecting signals and a power supply to the module. (Size: M3, clamp torque: 39 to 59 N cm {4 to 6 kg cm} [3.4 to 6.1 lb inches])					
		Name	ne Description				
		DATA	Data				
(4)	Terminal block	DG	Data gro	ound			
		FG	Frame g	round	Refer to Section "5 CONNECTION OF THE MASTER MODULE TO REMOTE I/O UNITS" for details of connection.		
		+24 V	Power s VDC (po	upply for transmitting 24 sitive)			
		24 G	Power supply for transmitting 24 VDC (negative)				
(5)	Terminal block	For connection to receive/send input/output signals (Size: M3, clamp torque: 39 to 59 N cm {4 to 6 kg cm} [3.4 to 6.1 lb inches]) Refer to Section 7 "SPECIFICATIONS OF REMOTE I/O UNITS" for details of connection.					
(6)	DIN rail mounting hooks	Hooks for mounting the unit on a DIN rail					
(7)	Unit mounting hole	Hole for mounting the unit on a panel (Size: M4, clamp torque: 78 to 118 N·cm {8 to 12 kg·cm} [6.9 to 10.4 lb·inches])					

5.1 Notes on Connection

In order to prevent unnecessary noise trouble, design the system with the following considerations paid to the communication lines and grounding lines of the I/O link.

(1) The power supply feeding the stabilized power supply of the I/O link must be in a separate system from the power lines for motors and inverters, or separated by an insulated transformer.



(2) In cases where equipment that generates high-frequency noise - such as an inverter - is installed in the same panelst, use twisted-pair cable for the transmission cables, and ground the wire shielding at the modules at both ends. (See Section (4).)



At T branches, connect the shielding with a terminal block. The shielding does not have to be grounded here.



(3) Keep transmission lines away from high-voltage power lines.If they must be run close together, separate them with a steel shield.



(4) Make the grounding wire connected to the FG terminal as thick as possible (2.0 mm^2) .

Carry out grounding as shown below. In particular, avoid common grounding with equipment that generates high-frequency noise.





- If the 24 VDC is mistakenly applied to a signal line (DATA, DG), the module will be destroyed. Be sure to check that the connections are correct before turning on the external power supply (24 VDC).
 - (5) Precautionary notes when grounding the twisted pair cable shield When the shield of a shielded transmission cable is grounded, the transmission waveform may be affected by the ground condition, and communication errors may be generated in long-distance systems. This phenomenon is caused by the connection between the ground and transmission signals at a high frequency via a condenser due to the static electricity capacity held between the shield and transmission cable. This becomes more likely to occur as the transmission distance gets longer, since the static electricity capacity increases. This phenomenon may also occur when only one side of the shield is grounded.



* There will be no effects from the ground if a cab tire cable is used, since it has no shield.

(a) Shield treatment

Effects from the grounded shield are dependent on the number of remote I/O modules connected and overall distance. Do not ground the shield if your system has a configuration in which the combination of number of remote I/O modules connected and overall distance is as shown in the table below.

Number of remote I/O modules connected	Overall distance range where grounding of shield should be avoided
1	—
2	150 m (492.15 ft.) or more
3	130 m (426.53 ft.) or more
4	110 m (360.91 ft.) or more
5	100 m (328.1 ft.) or more
6	90 m (295.29 ft.) or more
7	85 m (278.89 ft.) or more
8	75 m (246.08 ft.) or more
9	70 m (229.67 ft.) or more
10	65 m (213.27 ft.) or more
11	60 m (106 26 tt.) or more
12	60 m (196.86 ft.) or more
13	
14	55 m (180.46 ft.) or more
15	
16	50 m (164.05 ft.) or more

The number of modules indicated in the "number of remote I/O modules" is not the number of stations.

(b) Cable wiring



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5.2 Connections

The connection methods when using twisted pair cable and when using cabtyre cable are shown below.



(2) Connection with cabtyre cables



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REMARK

If one power supply provides power to multiple units, make sure that each unit receives sufficient voltage.





Connection methods using T-junctions are shown below.

Method for branching in the middle of a transmission line



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5.3 Mounting a Remote I/O Unit on a DIN Rail

This section describes how to mounting a remote I/O unit on a DIN rail.

- (1) Mounting procedure
 - (a) Engage the groove of the upper hook with the upper rail flange by lowering the unit onto the rail.
 - (b) Push the unit onto the rail and hook the lower hook onto the lower rail flange.



- (2) Removal procedure
 - (a) Prize down the hook on the bottom of the unit with a flat-tipped screwdriver.
 - (b) Pull the unit off the rail while the hook is pulled down.



POINT

The remote I/O module requires heat radiation. Therefore, it has to be installed on the panel in the above installation direction to ensure ventilation. Do not install it in other direction.

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5.4 Adding Remote I/O Units to an Existing System

This section explains how to add remote I/O units to an existing system.

- Three-step procedure -

- (1) Connect a cable to the remote I/O unit to be added.
- (2) Select a station number for the remote I/O unit.
- (3) Set the ONLINE STATION setting switches of the master module.



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6. SETTING STATION NUMBERS AND PROGRAMMING

This section describes how to set station numbers for and program control of remote I/O units.

6.1 Setting a Station Number

- Select a station number between 0 to F.
 Station numbers do not have to be select in the order of connection.
 Do not assign the same number to multiple units.
- (2) Set the ONLINE STATION setting switches accordingly.

6.2 Programming

The addresses used in a sequence program are determined by the I/O numbers of the master station and the station numbers of the remote I/O units. The I/O numbers of the master station are assigned the head addresses while the station numbers of the remote I/O units are sequentially assigned the following addresses.

[Example system configuration]



6. SETTING STATION NUMBERS AND PROGRAMMING

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of each re-			vice	Remark
mote I/O unit	mal nota- tion)	x	Y	
0	C0 / 1 2 3			AJ55TB3-4D (input 4-point unit)
1	4 5 6 7			AJ55TB2-8T (output 8-point unit)
2	8 9 A B		 	
3	C D E F			AJ55TB32-4DT (input 2-point/output 2-point unit) (4-point I/O combination units can use the first half two X and Y points only, not the second half two points.)
4	D0 1 2 3			AJ55TB32-8DT (input 4-point/output 4-point unit)
5	4 5 6 7			AJ55TB3-8D (input 8-point unit)
6	8 9 			
	C			
				—— The device used is indicated by .

The following chart shows the addresses assigned to remote I/O units.



Separate comments be assigned to X and Y devices with the same address (such as X10 and Y10) by using the extension comment function.

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7. TROUBLESHOOTING

This section describes how to troubleshoot communication problems (when input cannot be received or output cannot be sent).

Location	Condition	Corrective action		
	"24 V" is OFF.	Apply a voltage of 21.6 to 27.6 VDC to "+24, 24G".		
	"RUN" is OFF.	Abnormal communication has occurred with a remote I/O unit that was assigned a station number with ONLINE STATION setting switches. Identify the cause with the "SHORT", "OPEN", and "PARITY" indicators.		
	"SHORT" is ON.	Check the cable for a short between DATA and DG.		
LED of the master module	"OPEN" is ON.	Check for disconnection in a signal line (DATA or DG). Also check if the power supply to any remote I/O unit is OFF. Identify the faulty station with "ERROR STATION".		
	"PARITY" is ON.	Consider the possibility of noise interference since data received from a remote I/O unit is abnormal.		
	A LED between "0" and "F" of the ERROR STATION is ON.	Check the remote I/O unit corresponding to the LED.		
ONLINE STATION setting switches of the master module	One of the switches for a connected remote I/O unit is OFF.	Turn ON the switch.		
"ST. No." of re- mote I/O unit	The same station number is assigned to multiple units.	Change the setting.		
REMARK

The table below shows the error conditions that can be considered possible in the following system configuration based on LED statuses. It may help to identify errors in other system configurations.



	LED St						
	Master Module		Remote	I/O Units	System Status		
		A	A B		D		
	24V 0 8 RUN 1 9 5 SD 2 A R1 RD 3 B RA I SHORT 4 C O R OPEN 5 D R1 R PARITY 6 E O 7 F N	PW● RUN● SD● RD● ERR○	PW● RUN● SD● RD● ERR○	PW● RUN● SD● RD● ERR○	PW● RUN● SD● RD● ERR○	Normal	
"24 V" is ON.	24V 0 0 8 RUN 1 9 9 F 5 SD 2 A R F RD 3 B RA 1 SHORT 4 C 0 F PARITY 6 E 0 7 F N	PW RUN SD RD ERR	PW RUN SD RD ERR	PW RUN SD RD ERR	PW RUN SD RD ERR	Indicates power is not supplied or insufficient between +24V and -24G.	
"SHORT" is ON.	24V 0 8 RUN 1 9 1 5 SD 2 A R RD 3 B R SHORT 4 C 0 1 OPEN 5 D R PARITY 6 E 0 7 F N	PW● RUN○ SD○ RD● ERR○	PW● RUN○ SD○ RD● ERR○	PW● RUN () SD () RD ● ERR ()	PW● RUN ○ SD ○ RD ● ERR ○	Probably indicates a short between DATA and DG, but may indicate that DATA and DG have been connected the wrong way round.	

7. TROUBLESHOOTING

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	LED St						
	Master Module			I/O Units	System Condition		
	24V 0 0 8 RUN 1 9 15 SD 2 A C R RD 3 B R A SHORT 4 C 0 R 0PEN 5 D C R I PARITY 6 E 0 7 F N	A PW RUN SD RD ERR	B PW RUN SD RD ERR	C PW RUN SD RD ERR	PW RUN SD RD ERR	Indicates disconnection, malfunction of a remote I/O unit, or power supply OFF. Since the PWs of all the remote I/O units are OFF in this case, the power supply module may have been either turned OFF or failed.	
	24V 0 0 8 RUN 1 9 15 SD 2 A RI RD 3 B RA 1 SHORT 4 C 0 1 8 OPEN 5 D RI 9 PARITY 6 E 0 7 F N	PW● RUN● SD● RD● ERR○	PW● RUN () SD () RD () ERR ()	PW RUN SD RD ERR	PW RUN SD RD ERR	Indicates disconnection, malfunction of a remote I/O unit, or power supply OFF. Since the PWs of all the remote I/O units are ON, there must be a disconnection at the position marked by the cross.	
"OPEN" is ON.	24V 0 8 RUN 1 9 15 SD 2 A R RD 3 B R SHORT 4 C 0 R 0PEN 5 D R PARITY 6 E 0 7 F N	PW● RUN● SD● RD● ERR○	PW RUN SD RD ERR	PW RUN SD RD ERR	PW● RUN● SD● RD● ERR○	Indicates disconnection, malfunction of a remote I/O unit, or power supply OFF. Since the PWs of all the remote I/O units are ON, there must be a disconnection at the position marked by the cross.	
	24V 0 0 8 RUN 1 9 1 S SD 2 A R RD 3 B RA SHORT 4 C 0 R 0PEN 5 D R1 PARITY 6 E 0 7 F N	PW● RUN○ SD○ RD○ ERR○	PW RUN SD RD ERR	PW● RUN○ SD○ RD○ ERR○	PW● RUN○ SD○ RD○ ERR○	Indicates disconnection, malfunction of a remote I/O unit, or power supply OFF. Since the PWs of all the remote I/O units are ON, there must be a disconnection at the position marked by the cross.	

7. TROUBLESHOOTING

LED Status (: ON, O : OFF) **Remote I/O Units** System Status **Master Module** в С D Α 00 80 24V Indicates disconnection, 1 🔴 9013 PW PWO PW PW malfunction of a remote I/O SD AÔ RT 2〇 RUN RUN RUN RD 3 B RA SHORT 4 C 0 I OPEN 5 D R PARITY 6 C 0 unit, or power supply OFF. "OPEN" is SD SD() SD SD Since the PWs of all the SHORT 4 ON. remote I/O units are OFF, the RD RD RD RD power supply must have ERR been turned OFF or failed. 70 FО 24V 🌑 ٥0 8() RUN 1 9 E SD 2 A RI RD 3 B KA SHORT 4 C O OPEN 5 D R A remote I/O unit is abnormal. PW PW PW PW Since the ERROR LED of RUN RUN RUN RUN remote I/O unit C is lit. this "PARITY" is SD SD SD SD unit is considered unable to SHORT 4 ON. RD receive data from the master RD RD RD module correctly (possibly 6Ŏ EO PARITY ERR ERR ERR due to noise interference). 70 FО

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8. SPECIFICATIONS OF REMOTE I/O UNITS

8.1 Notes on Using Remote I/O Units

- (1) If a frequently-switching load or a coil load such as an electromagnet with a large capacity or a low power factor is used together with a contact output unit, the life of the output unit will be shortened.
- (2) The switching frequency for driving a load, L, in an output unit should never exceed "ON for at least 1 second and OFF for at least 1 second".
- (3) If a timer or counter is used with a DC/DC converter as the load, a rush current occurs either when the power supply is turned ON or at regular intervals during operation. This may cause a fault if a unit is selected by considering only the average current and not rush current. Accordingly, if such a load is used, connect a resistance or inductance in series with the load to decrease the influence of the rush current.



 (4) The following chart shows the relationship between the relay life of contact output units and the magnitude of switching currents. Applicable units: AJ55TB2-4R, AJ55TB2-8R, AJ55TB2-16R, AJ55TB32-4DR, AJ55TB32-8DR, and

AJ55TB32-16DR



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8.2 How to Read Model Names



8.3 How to Read Specification Tables

This section describes how to read the "Number of occupied stations" in the specification table of each remote I/O unit.

The shaded boxes indicates the number of addresses from "0" assigned to the unit.

The lower example below indicates an I/O combination assigned the same addresses for X and Y.



A guide to reading model names is presented below.

8.4 AJ55TB3-4D DC Input Unit



8.5 AJ55TB3-8D DC Input Unit



8.6 AJ55TB3-16D DC Input Unit



8.7 AJ55TB2-4T Transistor Output Unit



8.8 AJ55TB2-8T Transistor Output Unit



8.9 AJ55TB2-16T Transistor Output Unit



8.10 AJ55TB2-4R Contact Output Unit



8.11 AJ55TB2-8R Contact Output Unit



8.12 AJ55TB2-16R Contact Output Unit



8.13 AJ55TB32-4DT Input/Output Unit



8.14 AJ55TB32-8DT Input/Output Unit

	Type DC Input (Sink/Source Common Type)/Transistor Output Combination Unit								
Specification	<u> </u>	AJ55TB32-8DT				Appearance			
	Input \$	Specifications		Output	Specifications				
Number of input	t points	4 points	Number of outp points	ut	4 points				
Insulation meth	od	Photocoupler	Insulation meth		Photocoupler				
Rated input volt	tage	24 VDC	Rated load volt	age	24 VDC		-8D1	i	
Rated input current		Approx. 7 mA	Operating load voltage range		19.2 to 26.4 VDC (peak voltage: 26.4 V)		832-	2 4	
Operating voltage range		19.2 to 26.4 VDC (ripple: less than 5 %)	Max. load current		0.5 A/point, 2 A/ common		AJ55TB32	52	
Max. simultaneo input points	ous	100 %	Max. rush current 4 A for 10 ms. or less						
ON voltage/ON	current	14 V or greater/3.5 mA or greater	Leakage curren (when OFF)	Leakage current (when OFF) 0.1 mA or less		~ 🖾	NELSEC 19 2		
OFF voltage/ OFF current		6 V or less/1.7 mA or less	Max. voltage dr (when ON)	op	0.9 V DC or less (TYP.: 0.5 A) 1.5 VDC or less (max.: 0.5 A)		17	13	
Input resistance		Approx. 3.3 kΩ				」 - 囚		16	
Response	OFF→ ON	10 ms or less	Response	OFF→ ON	2 ms. or less		15		
time	ON→ OFF	10 ms or less	time	ON→ OFF	2 ms. or less (resistance load)		13		
Common metho	d	4 points/common	External	Voltage	19.2 to 26.4 VDC		=	12	
	power supply (I/O24V, I/O24G) 30 mA (TYP. 24 V Current DC/common) not inclu external load current		DC/common) not including the		б б				
			Surge suppressor		Zener diode			- ω	
			Common metho		4 points/common	20			
Number of occu stations		1 stations	0 1 2 3 X Y 0 1 2 3				MITSUBISHI	β 0 0 0 0 0 0 0 0 0 0 0 0 0	
I/O unit power supply	Voltage	15.6 to 27.6 VDC (peak voltage: 27.6 VDC)					DATA DATA	2	
(+24V, 24G)	Current					5 JU 0 3 6		61	
Weight (kg)[lb] External wiring									
Applicable wire		0.75 to 2 mm ²		iolaanig		1			
Applicable solde terminals	ərless	1.25-3, 1.25-YS3A, 2-S3, 2-YS3 V1.25-3, V1.25-YS3A, V2-S3, V2	A, 2-YS3A]			
				ernal Co	onnections		· · · · · · · · · · · · · · · · · · ·		
							Terminal No.	Signal Name	
		1 DATA 2 DG					TB1	DATA	
		See Section 5.					TB2 TB3	DG FG	
		4 24G					TB4	24G	
24 VDC 61/0246							TB5	+24V	
						TB6	I/024G		
					TB7 TB8	I/O24V COM-			
	3-wire s	ensor 9 X0 10 COM+					TB9	X0	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$						TB10	COM+		
						TB11	X1		
						TB12	COM-		
						TB13 TB14	X2 COM+		
						TB15	X3		
						TB16	COM-		
						TB17	YO		
	20 COM+						TB18 TB19	COM+ Y1	
21 Y2 22 COM +						TB20	COM+		
23/33						TB21	Y2		
24COM+					TB22	COM+			
	* C	onnect this to the COMB side i	f the sensor is a	a 2-wire	type.		TB23 TB24	Y3 COM+	
							COULT		

8. SPECIFICATIONS OF REMOTE I/O UNITS

8.15 AJ55TB32-16DT Input/Output Unit



8. SPECIFICATIONS OF REMOTE I/O UNITS

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8.16 AJ55TB32-4DR Input/Output Unit

Type DC Input (Sink/Source Common Type)/Transistor Output Combination Unit								
Specification AJ55TB32-4DT Appearance								e :
Input Specifications Output Specifications								
Number of input points 2 points		Number of output points		2 points				
Insulation method Photocoupler		Insulation method		Photocoupler	1			
Rated input voltage		24 VDC	Rated load voltage/current		24 VDC (resistance load) 40 VAC (COS¢-1) 2 A/point, 4 A/common			
Rated input curren	t	Approx. 7 mA	Min. switching load		5 VDC 1 mA			
Operating voltage	range	21.6 to 26.4 VDC (ripple: less than 5 %)	Max. switching voltage		250 VAC 110 VDC			
Max. simultaneous input points		100 %	Response time	OFF→ ON	10 ms or less		240R	
ON voltage/ON cu	rrent	14 V or greater/3.5 mA or greater		ON→ OFF	12 ms or less	- 🖸	AJ55T83240R	14 16
OFF voltage/OFF	current	6 V or less/1.7 mA or less	_	Mechani- cal	20 million operations or more	•	13.8EC /	12
Input resistance		Approx. 3.3 kΩ		Electrical	100 thousand operations or more at the rated switching voltage and current load.	-0	8 11	10
Response time	OFF→ ON	10 ms or less	Life		100 thousand operations or more at 200 VAC and 1.5 A, or 240 VAC or 1 A (COS¢=0.7)		5 7	8 8
	ON→ OFF	10 ms or less			100 thousand operations or more at 200 VAC and 1 A, or 240 VAC and 0.5 A (COS¢=0.35)	2 (1315) 2 (1315)		2 - 1
Common method		2 points/common			100 thousand operations or more at 24 VDC and 1A, or 100 VDC and 0.1 A (L/R=7 ms)	6 2028		
			Max. switching frequency		3600 times/hour			
			External power supply	Voltage	24 V DC ±10 %, ripple (4 Vp-p or less)]		
			(I/O24V, I/O24G) Current		12 mA (TYP. 24 V DC, all points ON)			
2			Surge suppressor		Zener diode	-		
		1 station 0	Common method		2 points/common	ļ		
1 station Number of occupied stations				ne latter two	o points connot be used.			
I/O unit power	Voltage	15.6 to 27.6 VDC (peak voltage: 27.6	VDC)					
supply (+24, 24G)	Current	40 mA	÷					
		0.2 [0.44]				-		
Weight (kg)[lb] External wiring sys	tem	16-point terminal block connector (M3		a tranemie		-		
Applicable wire siz		0.75 to 2 mm ²	screws/ including a	a transmis		4		
Applicable solderle		1.25-3, 1.25-YS3A, 2-S3, 2-YS3A,				1		:
terminals		V1.25-3, V1.25-YS3A, V2-S3, V2-YS3	A					
			External Conne	ctions				
		[Terminal No.	Signal
						ľ	TB1	Name DATA
		2 DG				ł	TB2	DG
	See	Section 5.				ŀ	TB3	FG
		4 24G]			-	TB4	24G
24 VDC Sink Source					ŀ	TB5	+24V	
$\frac{1}{\tau} = \frac{1}{\tau} = \frac{1}$				ľ	TB6	I/O24B		
				•	1	TB7	1/024A	
3-wire sensor 9 x0						1	TB8	COMB
						1	TB9	XO
							TB10	COMA
							TB11	X1
		L 13Y0					TB12	COM1
Í	[14COM1	$ \circ \bigcirc $	Ŷ			TB13	Y0
			RA RA				TB14	COM1
			122				TB15	Y1
			L	\		[TB16	COM2
	* Connect this to the COMB side if the sensor is a 2-wire type.							

8.17 AJ55TB32-8DR Input/Output Unit



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8.18 AJ55TB32-16DR Input/Output Unit



APPENDICES

APPENDIX 1 EXTERNAL DIMENSIONS

1.1 Master Module



Unit: mm (inch)

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(2) A1SJ51T64



Unit: mm (inch)

1.2 Remote I/O Unit



Model Name	Changed Dimensions				
woder Name	A	В			
AJ55TB[][]-4[][]	82 (3.23)	73 (2.87)			
AJ55TB[][]-8[][]	114 (4.4)	105 (4.09)			
AJ55TB[][]-16[][]	177 (6.97)	168 (6.61)			

Unit: mm (inch)

IMPORTANT

- (1) Design the configuration of a system to provide an external protective or safety inter locking circuit for the PLCs.
- (2) The components on the printed circuit boards will be damaged by static electricity, so avoid handling them directly. If it is necessary to handle them take the following precautions.
 - (a) Ground your body and the work bench.
 - (b) Do not touch the conductive areas of the printed circuit board and its electrical parts with non-grounded tools, etc.

Under no circumstances will Mitsubishi Electric be liable or responsible for any consequential damage that may arise as a result of the installation or use of this equipment.

All examples and diagrams shown in this manual are intended only as an aid to understanding the text, not to guarantee operation. Mitsubishi Electric will accept no responsibility for actual use of the product based on these illustrative examples.

Owing to the very great variety in possible applications of this equipment, you must satisfy yourself as to its suitability for your specific application.

<u>WARRANTY</u>

Please confirm the following product warranty details before using this product.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company.

However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing onsite that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place.

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 - 1. Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 - 2. Failure caused by unapproved modifications, etc., to the product by the user.
 - 3. When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 - 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 - 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 - 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 - 7. Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

2. Onerous repair term after discontinuation of production

- (1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued. Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

6. Product application

- (1) In using the Mitsubishi MELSEC programmable logic controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable logic controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- (2) The Mitsubishi programmable logic controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for Railway companies or Public service purposes shall be excluded from the programmable logic controller applications.

In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable logic controller range of applications. However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the users discretion.

MELSEC-I/O Link Remote I/O System Master Module Type AJ51T64/A1SJ51T64

User's Manual

MODEL A1SJ51T64-U-E

MODEL CODE

13J748

IB(NA)-66574-G(0604)MEE

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