MITSUBISHI

A1S66ADA Analog Input/output Module

Mitsubishi General Use PLC User's Manual (Hardware)

Thank you for buying the Mitsubishi General Use PLC MELSEC-A Series. Before use, please read this manual carefully and correctly operate the module with a sufficient understanding of the A series PLC functions and performance. Please place this manual in a location where it is available to end users.



MODEL A1S66ADA-U-H-E MODEL CODE 13JL42

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SAFETY PRECAUTIONS ●

(Read these precautions before using.)

When using Mitsubishi equipment, thoroughly read this manual and the associated manuals introduced in the manual. Also pay careful attention to safety and handle the module property.

The instructions given in this manual are concerned with this product. Refer to the User's Manual of the CPU module in use for details on the safety instructions for the programmable logic controller system.

These ● SAFETY PRECAUTIONS ● classify the safety precautions into two categories: "DANGER" and "CAUTION".

Procedures which may lead to a dangerous condition and cause death or serious injury if not carried out properly.

CAUTION Procedures which may lead to a dangerous condition and cause superficial to medium injury, or physical damage only, if not carried out properly.

Depending on circumstances, procedures indicated by **ACAUTION** may also be linked to serious results.

In any case, it is important to follow the directions for usage.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

 In case of the external power supply failure or the programmable controller (PLC) failure, set up a safety circuit outside the PLC so that the entire system can operate safely. The mis-output and malfunction may cause an accident.

- Use the PLC in an environment that meets the general specifications contained in this manual. Using this PLC in an environment outside the range of the general specifications could result in electric shock, fires, malfunctions, and damage to or deterioration of the product.
- Do not bunch the control wires with the main circuit or power wires, or install them close to each other. They should be installed 100 mm (3.9 inch) or more from each other. Failure to do so may result in noise that would cause malfunctions.
- At power ON/OFF, voltage or current may instantaneously be output from the output terminal of this module. In such case, wait until the analog output becomes stable to start controlling the external device.

[INSTALLATION PRECAUTIONS]

- Insert the tabs at the bottom of the module into the mounting holes in the base unit.
- If the module is not properly installed, it may result in malfunctions, failure, or fallout.
- Do not directory touch the module's conductive parts. Doing so could cause malfunctions or failure in the module.

[WIRING PRECAUTIONS]

- Ground the AG and FG terminals to the protected grounding conductor when there are a lot of noise. Failure to ground these terminals may cause malfunctions.
- When wiring PLC, check the rated voltage and terminal layout of the wiring, and make sure the wiring is done correctly. Connecting a power supply that differs from the rated voltage or wiring it incorrectly may cause fires or failure.
- Tighten the terminal screws within the range of specified torque.
 If the terminal screws are loose, it may result in short circuits or malfunctions.

Tightening the screws too far may cause damage to the screw, resulting in short circuits, or malfunctions.

 Be sure there are no foreign substances such as sawdust or wiring debris inside the module. Such debris could cause fires, failure, malfunctions.

[STARTING AND MAINTENANCE PRECAUTIONS]

- Do not touch the connector while the power is on. Doing so could cause malfunctions.
- Make sure to switch all phases of the external power supply off before cleaning or re-tightening terminal screws. If you do not switch off the external power supply, it will cause failure or malfunctions of the module.
- Do not disassemble or modify the modules. Doing so could cause failure, malfunctions, injury, or fires.
- Make sure to switch all phases of the external power supply off before mounting or removing the module. If you do not switch off the external power supply, it will cause failure or malfunctions of the module.
- Do not install/remove the terminal block more than 50 times after the first use of the product. (IEC 61131-2 compliant)
- Before handling the module, always touch grounded metal, etc. to discharge static electricity from the human body.
 Failure to do so can cause the module to fail or malfunction.

[OPERATING PRECAUTIONS]

() DANGER

 Do not output (turn ON) the "usage disable" signal as an output signal to special modules from the PLC CPU.
 Outputting the "usage disable" signal may cause PLC system malfunctions.

[DISPOSAL PRECAUTIONS]

When disposing of this product, treat it as industrial waste.

About This Manual

The following product manuals are available.

Related Manual

Manual Name	(Type code)
Analog Input/output Medule tune A1966ADA Lleave Menual	IB-66819
Analog Input/output Module type A1S66ADA User's Manual	(13JL41)

Please read A1S66ADA Module User's Manual before using this module.

1. Overview

This manual describes the handling and specifications of the A1S66ADA type Analog I/O Module (hereafter referred to as A1S66ADA), which is utilized in combination with the MELSEC-A series CPU module (hereafter referred to as PLC CPU).

- (1) Product in the same package
- After unpacking, please confirm that the following product is contained.

Product Name	No. of Items
Analog Input/output Module type A1S66ADA	1

2. Performance Specifications

The performance specifications of the A1S66ADA are described below:

	Item	Performance Specifications									
	_	Voltage output					Current output				
	Digital input	0 to 4000 (12-bit binary value)									
	Analog output	-10 to 10VDC 0 to 20mADC									
		(Exte	rnal load	resistar	ce : 2k	Ω to 1	1MΩ)	(Ext	emal load i 0Ω to 60	resistance :	
				Δnal	og out	out				log output	
		Digital	0 to 10V	0 to 5		o 5V	-10 to	Digita		4 to	
		input	range	range		inge	10V	inpu			
	I/O					J .	range		range	e range	
	characteristics	0	0V	0V	1	1V	-10V	0	0mA	4mA	
	Gilardotoriotido	1000	2.5V	1.25\		2V	-5V	1000			
		2000	5V	2.5V		3V	0V	2000			
D/A		3000	7.5V	3.75		4V	5V	3000			
conversion	Maximum	4000	10V	5V		5V	10V	4000) 20m/	A 20mA	
	resolution		2.5mV	1.25m	V 1.0	OmV	5.0m\	′ 🖊	5μΑ	4μΑ	
	Conversion	·							_		
	speed	240µs/2 channels or less (Sampling : 80µs/1 channel)									
	Absolute										
	maximum			Volta	age : ±	12V	Curren	t : +28m/	4		
	output										
	Output short					Pre	sent				
	protection										
	Analog output points					2 cha	annels				
	Offset/gain	Adjuet	the two o	hannele	simul	tanec	usly with	the con	trol knob c	n the	
	adjustment								done on-li		
A/D									ice: 1MΩ)		
conversion	Analog input							esistance			
	Digital output			0 t	o 4095	i (12-b	vit binar	y value)			
			Analog	innut (v	oltage)			Analo	g input		
		Analog input (voltage)					(cur	rent)	Digital		
		0 to 10V			o 5V	-10 to		0 to	4 to	output	
		range	range	e ra	inge	ran	nge	20mA	20mA		
	I/O characteristics	0V	0V	_	1V	4	0V	range	range 4mA	0	
	Gildidoteriotico	2.5V	1.25		1V 2V		5V	0mA 5mA	4mA 8mA	1000	
		2.5V	2.5V		2 V 3 V		v	10mA	12mA	2000	
		7.5V	3.75		4V		V	15mA	16mA	3000	
		10V	5V		5V	10	V	20mA	20mA	4000	
	Maximum	2.5mV	1.25m	V 1.	0mV	5.0	mV	5μΑ	4μA		
	resolution										
	Conversion speed	400μs/4 channels or less (Sampling : 80μs/1 channel)									
	Absolute	· - · · /									
	maximum	Voltage : ±15V Current : ±30mA									
	input	Voltage . ± 10 V Outrent . ±0011A									
	Analog input	4 channels									
	points	4 channels									
	Offset/gain	Adjust the four channels simultaneously with the control knob on the									
	adjustment	front side of the module. Check the digital output value making the adjustments.						iue on-line	e while		
	1		conversio			oltage	e output		Current	outout	
			icy agains				anges)		(All ra		
Dverall com	11201		mum valu		±1.0 % (±100 mV)			<i>V</i>)	±1.0 % (:		
Overall accu	nacy	A/D	conversio	n							
			racy agair				ł	±1.0 % (±	40)		
			full scale								
nsulation m	ethod	Photocoupler isolation between I/O terminals and the PC power supply.									
Jumber of a		Between each channel: No isolation									
Number of occupying I/O points		64 points (Input 64 points, output 64 points)									
Connecting terminal base		20-point terminal base (M3.5 × 7 screws)									
Applicable w		0.75 to 1.25mm ²									
		R1.25 - 3 1.25 - YS3 2 - 3.5 2 - YS3A									
Applicable solderless erminal		V1.25 - M3 V1.25 - YS3A V2 - S3 V2 - YS3A									
	ent consumption										
5VDC)(A)						0.:	- 1				
External	Voltage (V)				21.	6DC to	o 26.4D	26.4DC			
		0.16									
	Current					0	16				
	Current consumption (A)						16 33				

Poin	:
When	itilizing the peripheral device to assign the I/O numbers, set
it as a	64-point output module.

Refer to the User's Manual of the PLC CPU for the general specifications.

3. Part Identification and Settings

3.1 Part Identification



NO.	Name	Description
1)	RUN LED	Indicates the operating conditions of the A1S66ADA On: Power is ON
		Off: Power is OFF
2)	D/A conversion offset control knob	Used when making a fine adjustment of the D/A conversion offset.
	D/A OFFSET	The offset value is increased by turning the control knob to the right. The offset value is decreased by turning the control knob to the left.
3)	D/A conversion gain control knob D/A GAIN	Used when making a fine adjustment of the D/A conversion gain. The gain value is increased by turning the control knob to the right. The gain value is decreased by
4)	A/D conversion offset control knob A/D OFFSET	turning the control knob to the left. Used when making a fine adjustment of the A/D conversion offset. The offset value is increased by turning the control knob to the right. The offset value is decreased by
5)	A/D conversion gain control knob A/D GAIN	turning the control knob to the left. Used when making a fine adjustment of the A/D conversion gain. The gain value is increased by turning the control knob to the right. The gain value is decreased by turning the control knob to the left.
6)	Analog output terminal (CH1, CH2)	Outputs the analog values (voltage/current) of CH1 to CH2. Refer to Section 5.2 on the wiring method.
7)	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Inputs the analog values (voltage/current) of CH3 to CH6. Refer to Section 5.2 on the wiring method.
8)	Analog ground terminal	The ground terminal of the analog signal (Refer to Section 5.2 on the wiring method.)
9)	Frame ground terminal	The ground terminal of the shielded cable (Refer to Section 5.2 on the wiring method.)
10)	Power supply input terminal	Connect 24VDC at the input terminal of the power supply.
11)	Analog-output range switching setting pin 0 ~ 10 ∨ 000000 0 - 5 ∨ 000000 1 - 5 ∨ 000000 -10 - 10 ∨ 000000	Set the analog output range. CH1, CH2 common. When setting the current output range, set as follows: When switching to 0 to 20 mA → Set a jumper at a position between 0 V and 5 V. When switching to 4 to 20 mA → Set a jumper at a position between 1 V and 5 V. Set the jumper as it always makes a line. (Set it with the jumper) (Setting at shipment : 0 to 10V range) (Example) When the analog output range is set to 0 to 10 V or 0 to 20 mA, the jumper should be set as follows: Distributed by the set as follows: 0 to 10 V or 0 to 20 mA, the jumper 0 - to V © 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

NO.	Name	Description
12)	Analog-input voltage/current switching setting pin CH3 0 0 0 CH4 0 0 0 0 0 CH4 0 0 0 CH4 0 0 CH4 0 CH4 0 CH4 0 CH4	Set the analog input (voltage input or current input) for each channel (CH3 to CH6). (Set it with the jumper) (Setting at shipment : V) For voltage input setting : V For current input setting : I
13)	Analog-input range switching setting pin 0 0 0 0 0 ~ 10V 0 0 0 0 0 ~ 5V 0 0 0 0 1 - 5V A/D 0 0 0 0	Set the analog output range. CH3 to CH6 common. When setting the current output range, set as follows: When switching to 0 to 20 mA \rightarrow Set a jumper at a position between 0 V and 5 V. When switching to 4 to 20 mA \rightarrow Set a jumper at a position between 1 V and 5 V. (Setting at shipment : 0 to 10V range) (Set it with the jumper) (Example) When the analog input range is set to -10 to 10 V or 4 to 20 mA, the jumper should be set as follows. AD $\downarrow 0 = 0 = 0 = 0 = 0$ $\downarrow $
14)	Terminal block	Numbers in a graphic indicate terminal numbers.

4. Loading and Installation

4.1 Handling Precautions

- (1) Do not drop or put a great impact on the module case and the terminal block because they are made of resin
- (2) Do not take the printed circuit board of the module out of the case. It may result in a failure.
- (3) Be careful not to let foreign matter such as filings or wire chips get inside the module while wiring. Remove all foreign matters if any get inside
- (4) Tighten the module installation screws and terminal screws within the range as follows:

Screw Area	Tightening Torque Range N·cm
Module fixing screws (M4 screw)	78 to 118N·cm
Terminal block terminal screws (M3.5 screw)	59 to 88N·cm
Terminal block installation screws (M4 screw)	78 to 118N·cm

4.2 Installation and Removal of the Shield Cover

It is necessary to install the shield cover when using Procedures for installing and removing the shield cover are described below.

(1) Installation



To install the shield cover to the module, install the cover to the terminal side first as shown in the figure, then it will be completed by pushing the cover to the module and tightening the shield fixing screw

(2) Removal



To remove the cover from the module, remove the shield fixing screw first and insert the tip of a flat-tip screwdriver into the removal hole as shown in the figure, then move the screwdriver towards the rear of the module to separate the clip from the removal hole and remove the cover.

4.3 Installation Environment

Never install the A series in the following environments:

- (1) Locations where the ambient temperature is outside the range of 0 to 55°C.
- (2) Locations where the ambient humidity is outside the range of 10 to 90% RH.
- (3) Locations where dew condensation takes place due to sudden temperature changes
- (4) Locations where there are corrosive and/or combustible gasses.
- (5) Locations where there is a high level of conductive powder (such as dust and iron filings, oil mist, salt, and organic solvents).
- (6) Locations exposed to the direct rays of the sun.
- $(7)\;$ Locations where strong power and magnetic fields are generated. (8) Locations where vibration and shock are directly transmitted to the main module.

5.2 Wiring Between the A1S66ADA and the External Devices

The following shows the wiring method for the A1S66ADA. (1) CH1 and CH2

(a) For voltage output





- *1 Use a two-core twisted shield line for the power cable.
- *2 When noise or ripple occurs with the external cable, connect a condenser with 0.1 to 0.47μ FWV to the input terminal of the external device.

Important	
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The voltage and current output can not be used simultaneously

on the same channel.

In the event it is used, the internal elements are destroyed;

therefore always open unused terminals.

5. Wiring

The following describes the precautionary items on wiring as well as wiring to the external devices.

5.1 Precautions when Wiring

To obtain the maximum performance from the functions of A1S66ADA and improve the system reliability, a wiring with the high durability against the noise is required. The external wiring precautions described below make more improvement in the wiring not to be affected by the noise.

- (1) Use separate cables for the AC and the analog input to the A1S66ADA, in order not to be affected by the AC side surge or conductivity.
- (2) Do not bundle or place the cable close to the main circuit line, high voltage line or load carrying wires from other than the PLC. It is influenced more easily by the noise, surge, or conductivity.
- (3) Place a one-point grounding on the PLC side for the shield line or shield cable. However, depending on the external noise conditions, it may be better to have a grounding externally.

(2) CH3 to CH6



- *1 Use a two-core twisted shield line for the power cable.
- *2 Indicates the A1S66ADA input resistance.
- *3 When noise or ripple occurs with the external cable, connect a condenser with about 0.1 to 0.47 μF (25V or more voltage resistance parts) between the terminal V+I+ and V-I-.
- *4 The FG terminal of the power supply module should always be grounded.
- *5 Make sure to connect between the FG of the power supply module and the FG of A1S66ADA.
- *6 Due to noise in the environment, AG terminal may attain better accuracy when grounded.

Point

The FG terminal of A1S66ADA and the FG terminal of the PLC power supply module are not connected.

6. External Dimensions Diagram



Warranty

Mitsubishi will not be held liable for damage caused by factors found not to be the cause of Mitsubishi; machine damage or lost profits caused by faults in the Mitsubishi products; damage, secondary damage, accident compensation caused by special factors unpredictable by Mitsubishi; damages to products other than Mitsubishi products; and to other duties. A For safe use

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life
- · Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi.
- This product has been manufactured under strict quality control. However, when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

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